Abstract

Transactional Memory (TM) is a powerful abstraction for synchronizing activities of different threads through transactions. TM implementations guaranteeing Disjoint-Access Parallelism (DAP) are highly desirable on current multi-core architectures because they can exploit low-level parallelism. Unfortunately, a number of results have been proved concerning the impossibility of implementing TMs that guarantee different variants of the DAP property, as well as alternative consistency and liveness criteria.

This paper looks for a breach in the wall of existing impossibility results, by attempting to identify the strongest consistency and liveness guarantees that a TM can ensure while remaining scalable — by ensuring DAP — and maximizing efficiency in read-dominated workloads — by having invisible and wait-free read-only transactions.

We show that implementing such a TM is indeed possible if one adopts as consistency criterion Extended Update Serializability, combined with a weaker variant of real-time order, which we name Witnessable Real Time Order. Interestingly the resulting semantics share a number of similarities with classic TM safety criteria like Opacity and Virtual World Consistency, while allowing for scalable and efficient implementations.

Along the path of designing this protocol, we report two impossibility results related to ensuring real-time order in a weakly DAP TM that guarantees wait-free read-only transactions considering different progress criteria and both visible and invisible read-only transactions.

Finally, we also provide a lower bound on the space complexity of a strictly DAP TM that ensures a very weak consistency criterion, called Consistent View. We leverage this result to prove that the proposed protocol is optimal in terms of per object version spatial utilization.

Keywords: Software Transactional Memory, Disjoint-Access Parallelism, Real-Time Order.
1 Introduction

Over the last decade, Transactional Memory (TM) [27] has emerged as an attractive paradigm for simplifying parallel programming. The recent integration of TM in hardware by major chip vendors (e.g., Intel, IBM), together with the development of dedicated GCC extensions for TM (i.e., GCC-4.7) has significantly increased TM’s traction, paving the way for its adoption in mainstream software projects.

A property that is deemed as crucial for the scalability of a TM implementation is its ability to avoid any contention on shared objects, also called base objects, between transactions that access disjoint data sets – a property called disjoint-access parallelism (or DAP) [20]. Also, since many real-world workloads are often read-dominated, another aspect that has a strong impact on performance of TM algorithms is to what extent these optimize the processing of read-only transactions. In this sense, two main properties are regarded as particularly important for read-only transactions: wait-freedom, i.e. (read-only) transactions should never be blocked or aborted, and invisible reads, i.e. the execution of a read operation issued by a read-only transaction should never trigger the update of any data or base object. We succinctly denote the former property as WFRO and the latter as IRO, and their union as WFIRO.

Unfortunately, the literature on theory of TM has developed a number of impossibility results related to implementing TM algorithms that guarantee different variants of the DAP property, as well as alternative consistency and liveness criteria [4, 25, 15, 13, 8]. For instance, Attiya et al. [4] proved that an TM cannot be weak DAP, ensure obstruction freedom and WFIRO, while guaranteeing Strict Serializability or even Snapshot Isolation. More recently, Bushkov et al. [8] proved the impossibility of implementing a strict DAP TM that guarantees obstruction freedom and a very weak consistency criterion, namely Weak Adaptive Consistency.

In this paper we attempt to find a breach in this wall of impossibility results, seeking an answer to the following question: what are the strongest consistency and liveness guarantees that a TM can ensure while remaining scalable — by ensuring DAP — and maximizing efficiency in read-dominated workloads — by having invisible and wait-free read-only transactions? Our search space considers the Cartesian product of the consistency criteria specified by Adya’s hierarchy [1] and of a set of liveness properties that comprises both TM-specific criteria (weak and strong progressiveness [17]) as well as classical progress criteria originally defined for shared objects (obstruction-, lock- and wait-freedom [18]).

Along the path that will lead us to answer the above question, we first prove 2 novel impossibility results. We show that if one selects any consistency criterion that ensures Real Time Order (RTO), and independently of the isolation guarantees ensured among concurrent transactions, it is impossible to ensure also WFRO, obstruction-freedom for update transactions and the weakest form of DAP. We also show that even assuming weakly progressive update transactions [17], we are still faced with an impossibility result if we want the TM to preserve the efficiency of read-only transactions by having them performing invisible reads.

These results highlight the necessity of relaxing RTO in order to implement a scalable TM that maximizes the efficiency of read-only transactions by jointly guaranteeing DAP and WFIRO. This leads us to introduce a weaker variant of RTO, which we name Witnessable Real Time Order (WRTO), which demands that the real time order relation between two transactions is enforced only if these exhibit a data conflict. WRTO preserves some desirable properties of classic RTO, such as that if a transaction $T$ running solo issues a read on a data item $x$, $T$ is guaranteed to return the version of $x$ produced by the last transaction to have committed before $T$’s start and updated $x$. On the other hand, WRTO admits schedules in which a set of sequential transactions $T_2, T_3$ accessing disjoint data sets can be observed in an arbitrary order, which possibly contradicts their RTO relations, by a concurrent transaction $T_4$ (as exemplified by history $H_{WRTO}$ in Figure 1). The WRTO property is indeed designed in order to be amenable for DAP implementations, as it demands that RTO is enforced only among conflicting transactions (that clearly access non-disjoint data sets), and which can track such ordering relations via some shared base-object (which serves as a witness) without violating DAP.

We show that, by adopting WRTO, it is in fact possible to implement a WFIRO TM that guarantees the strongest variant of DAP, strong progressiveness and a consistency criterion whose semantics is very close to those provided by popular safety properties for TM, such as Opacity [16] or Virtual World Consistency [19]. This consistency criterion, known in the literature as Extended Update Serializability (EUS) [24] or PL-3U.
extended to executing transactions [1], guarantees the serializability of the history of committed update transactions — hence ensuring the absence of anomalies for transactions that update the state of the system. Further, analogously to Opacity or Virtual World Consistency, EUS provides guarantees also on transactions that eventually abort, ensuring that the snapshots that they observe must be producible by some equivalent serialization of the history of (committed) update transactions. On the other hand, EUS admits non-serializable histories analogously to Opacity or Virtual World Consistency, EUS provides guarantees also on transactions that even-

Figure 1: Example of histories accepted by EUS and WRTO (dependence edges shown with thin lines, (W)RTO edges with thick lines).

2 Formalism and Assumptions

System and transaction execution model. We consider an asynchronous shared memory system composed of \( N_p \) processes (or threads) \( p_1, \ldots, p_{N_p} \) that communicate by executing transactions and may fail by crashing.

A transaction starts with a \emph{begin} operation, and can be followed by a sequence of \emph{read} and \emph{write} operations on shared objects, and finally completed by either a \emph{commit} (or \emph{abort}) operation. We denote with \( x_i \) the version of the object \( x \) committed by a transaction \( T_i \), where \( i \) is an index that univocally identifies a transaction. We note \( op_i \) an operation issued by \( T_i \) and with \( OP_i \) the set of operations issued by \( T_i \), which is assumed to be totally ordered. We denote the write operation of \( T_i \) on object \( x \) with \( W_i(x) \), and use the notation \( R_i(x) \) to indicate that transaction \( T_i \) has read version \( x_j \) of \( x \) written by transaction \( T_j \). We say that two operations \( op_i \) and \( op_j \), with \( i \neq j \), are conflicting if they access a common object \( x \) and at least one of them is a write.

History and DSG. A history \( \mathcal{H} \) over a set of transactions \( \{T_1, \ldots, T_n\} \) is a partial order \( \prec_{\mathcal{H}} \) defined over the set of operations \( OP_{\mathcal{H}} = \bigcup_{i=1}^{n} OP_i \) such that i) \( \prec_{\mathcal{H}} \) preserves the ordering of the operations of each transaction \( T_i \) \((\prec_{\mathcal{H}} \supseteq \bigcup_{i=1}^{n} OP_i) \), and ii) for any two conflicting operations \( op_i, op_j \in \mathcal{H} \), either \( op_i \prec_{\mathcal{H}} op_j \) or \( op_j \prec_{\mathcal{H}} op_i \). In addition \( \mathcal{H} \) implicitly induces a total order \( \ll \) on the committed versions of each object [1].

We define the Direct Serialization Graph \( DSG(\mathcal{H}) \) on a history \( \mathcal{H} \) (as in [1, 7]) as a direct graph with a vertex for each transaction \( T_i \) in \( \mathcal{H} \) and a directed edge from \( T_i \) to \( T_j \), where \( i \neq j \), if there exist two operations \( op_i, op_j \in OP_\mathcal{H} \) such that \( op_i \prec_{\mathcal{H}} op_j \) or \( op_j \prec_{\mathcal{H}} op_i \). As in [1], we distinguish three types of edges depending on the type of conflicts between \( T_i \) and \( T_j \):

- Direct read-dependence edge, if there exists an object \( x \) such that both \( W_i(x_i) \) and \( R_j(x_i) \) are in \( \mathcal{H} \). We say that \( T_j \) directly read-depends on \( T_i \) and we use the notation \( T_i \xrightarrow{\text{rr}} T_j \).
- Direct write-dependence edge, if there exists an object \( x \) such that both \( W_i(x_i) \) and \( R_j(x_j) \) are in \( \mathcal{H} \) and \( x_j \) immediately follows \( x_i \) in the total order defined by \( \ll \). We say that \( T_j \) directly write-depends on \( T_i \)
and we use the notation $T_i \xrightarrow{wu} T_j$.

- **Direct anti-dependence edge**, if there exists an object $x$ and a committed transaction $T_k$ in $\cal H$, with $k \neq i$ and $k \neq j$, such that both $R_i(x_k)$ and $W_j(x)$ are in $\cal H$ and $x_j$ immediately follows $x_k$ in the total order defined by $\ll$. We say that $T_j$ directly anti-depends on $T_i$ and we use the notation $T_i \xrightarrow{ra} T_j$.

**DAP and Invisible Reads.** In this paper we rely on two versions of disjoint-access parallelism (DAP), namely **strict disjoint-access parallelism** [15] (SDAP), and **weak disjoint-access parallelism** [4] (WDAP). A TM ensures SDAP if two transactions conflict on a common base object only if they access some common transactional object. As base object we mean any information (data and meta-data) associated with a high-level transactional object, that is accessible by transactions. On the other hand, a TM implementation ensures WDAP if two concurrent transactions $T_1$ and $T_2$ conflict on a common base object only if there is a path that connect the two transactions in the undirected version of the DSG of the minimal execution interval containing the execution intervals of $T_1$ and $T_2$ [4].

A read operation $R_i$ performed by $T_i$ is called **invisible** if it does not apply a write operation on any base object. Otherwise it is called **visible**. A read-only transaction performing only invisible reads, is called invisible.

**Progress guarantees.** A TM is **strongly progressive** [17] if (i) transactions executed by the TM that do not encounter any conflict must be able to commit, and (ii) at least one transaction among a set of transactions that only conflict on one common object must be able to commit. A weaker form of this progress condition, i.e., **weak progressiveness**, has also been defined in [17], which requires that a transaction can only abort if it experiences a conflict.

We consider two additional liveness properties, namely **obstruction-freedom** and **wait-freedom**. A TM is obstruction-free [15] if for every history $\cal H$ executed by the TM, a transaction $T_i \in \cal H$ is forcefully aborted only if $T_i$ encounters step contention. We have a step contention for a transaction $T_i$ if a process different from the one running $T_i$ executes a step after the first operation of $T_i$ and before its completion (whether commit or abort). As for wait-freedom we adopt the definition adapted for TM that was introduced in Attiya et al. [4]: a TM is wait-free [18] if any transaction executed by a non-faulty process eventually commits in a finite number of steps despite the behavior of concurrent transactions. We consider processes as non-faulty if they do not crash and they are not parasitic, i.e., they eventually request the commit of every transaction that they start unless they crash before [9].

**Consistency criteria.** Throughout our paper we will refer to the hierarchy of consistency criteria defined by Adya [1], which encompass a number of criteria defined in terms of the anomalies that they proscribe.

The minimum correctness level considered in this paper is the well known Read Committed level [6] included by the formalization of the PL-2 level in [1]. PL-2 includes both PL-2+ and EUS, and it proscribes the anomalies G1a, G1b and G1c. Prescribing G1a means that values created by transactions that abort cannot be observed. Anomaly G1b allows for observing intermediate non-committed values. Finally, avoiding anomaly G1c ensures the absence of an oriented cycle of all dependence edges in the $\text{DSG}(\cal H^c)$ graph built on the history $\cal H^c$, where $\cal H^c$ is derived from $\cal H$ by removing aborted and executing (i.e. ongoing) transactions. Informally, an TM implementation that guarantees PL-2, allows a transaction $T_k$ to only read the updates of transactions that have committed by the time $T_k$ commits.

We consider also a correctness criterion stronger than PL-2, named **Consistent View** (PL-2+) [1]. Besides G1a, G1b, G1c, PL-2+ prevents the G-single anomaly, hence avoiding that $\text{DSG}(\cal H^c)$ contains an oriented cycle with exactly one anti-dependence edge. Roughly speaking, PL-2+ demands that transactions are always provided with a consistent view of the transactional state, as long as write transactions apply their changes consistently.

Finally, EUS [24], also called PL-3U extended to executing transactions by Adya [1], is a consistency criterion stronger than PL-2+. EUS proscribes the same anomalies of PL-2 as well as Extended G-update, namely the $\text{DSG}(\cal H^\text{upc}_T)$ graph built on the committed write transactions in $\cal H$ plus transaction $T_k$ in $\cal H$ contains an oriented cycle with one or more anti-dependence edges.

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We adopt the definition provided in [4] because we want to relate the results presented in this paper with the ones presented in [4]. For a formal definition of the strongest progress condition specifically defined for (S)TM, i.e., **local progress**, refer to the work in [9].
The graph considered in the Extended G-update anomaly only includes committed write transactions and at most one additional transaction \( T_k \) belonging to one among the following categories: aborted, executing or read-only transactions. EUS admits non-serializable histories, as illustrated in history \( \mathcal{H}_{EUS} \) of Figure 1, which allows two read-only transactions \((T_3 \text{ and } T_1)\) in \( \mathcal{H}_{EUS} \) to observe in different orders the commits of non-conflicting update transactions \((T_2 \text{ and } T_3)\) in \( \mathcal{H}_{EUS} \).

On the other hand, the only discrepancies in the serialization orders observable by read-only, executing and aborted transactions under EUS are imputable to the re-ordering of update transactions that neither conflict (directly or transitively) on data, nor are causally dependent. In other words, the only discrepancies perceivable by end-users are associated with the ordering of logically independent concurrent events, which has typically no impact on the correctness of a wide range of real-world applications [1].

**Real-Time Order and Witnessable Real-Time Order.** Real-Time Order (RTO) is a partial order defined over a transaction history \( \mathcal{H} \), noted \( \prec_{\mathcal{H}}^{RTO} \), which reflects the happened-before relation between transactions in a history. A transaction \( T_q \) is ordered before \( T_k \) in RTO, \( T_q \prec_{\mathcal{H}}^{RTO} T_k \), if the commit operation \( c_q \) of \( T_q \) precedes the begin operation \( b_k \) of \( T_k \) in \( \mathcal{H} \).

We introduce a weaker variant of RTO, which we call **Witnessable Real Time Order** (WRTO), which tracks happened-before relations exclusively between directly conflicting transactions, or formally \( T_q \prec_{\mathcal{H}}^{WRTO} T_k \) if \( T_q \prec_{\mathcal{H}}^{RTO} T_k \) and \( T_q \) and \( T_k \) conflict.

A history \( \mathcal{H} \) preserves RTO, respectively WRTO, if after having included in DSG(\( \mathcal{H} \)) a direct edge \( \forall T_q, T_k \) in \( \mathcal{H} \), such that \( T_q \prec_{\mathcal{H}}^{RTO} T_k \), respectively \( T_q \prec_{\mathcal{H}}^{WRTO} T_k \), then the resulting graph does not contain cycles that include \( T_q \) and \( T_k \). An example history that ensures WRTO but not RTO is shown in Figure 1 (\( \mathcal{H}_{WRTO} \)), in which \( T_q \) runs concurrently with two update transactions \( T_3 \) and \( T_2 \), while \( T_2 \) runs sequentially after \( T_3 \) (hence \( T_2 \prec_{\mathcal{H}}^{WRTO} T_3 \)) and update disjoint data sets (hence \( T_2 \prec_{\mathcal{H}}^{WRTO} T_3 \)), observes the committed versions of \( T_2 \) but not those of \( T_3 \).

### 3 The Impossibility Results on DAP and Real-Time Order

In this Section we try to understand whether it is possible to combine RTO and a reasonable consistent criterion in DAP TM that guarantees also desirable guarantees such as WFRO and IRO.

To answer this, we prove that a DAP TM cannot guarantee both RTO and WFRO if the progress requirement for write transactions is obstruction-freedom (Theorem 1). The result is independent of the provided consistency level and the visibility of read-only transactions. The intuition underlying the proof is that any TM that does not violate the RTO between any pair of transactions having a direct conflict (i.e., WRTO), then the TM must also admit a history that violates RTO.

**Theorem 1** Given a WDAP, obstruction-free TM, that guarantees WFRO, \( \exists \mathcal{H} \) accepted by the TM such that \( \mathcal{H} \) does not preserve RTO.

**Proof.** The proof follows by contradiction and throughout the proof we assume that two different transactions are executed by two distinct processes. We assume by contradiction that \( \forall \mathcal{H} \) accepted by the TM \( \mathcal{H} \) preserves RTO. Hence, the TM must at least preserve WRTO.

Therefore every read operation in \( \mathcal{H} \) must return the last value committed at the time the operation was executed. Formally, for each transaction \( T_h \) in \( \mathcal{H} \) and object \( x \), if \( r_h(x_j) \) is in \( \mathcal{H} \), then \( \exists x_k \), where \( x_j \ll x_k \), at the time \( r_h(x_j) \) begins its execution.

This is mandatory because of the following two reasons: (i) As the system must ensure WDAP, and as we are assuming that the set of data items to be accessed during the transactions execution is not a priori known, then during the begin a transaction \( T_h \) cannot access any base object in order to determine the set of transactions that have already committed before \( T_h \) started. If it did, in fact, there always exists a history in which \( T_h \) accesses a base object \( y \) that is being updated by a transaction \( T_q \), which registers its commit event in \( y \) and such that \( T_q \) is not connected to \( T_h \) via a path in the conflict graph, hence violating WDAP. (ii) If the last committed value is not returned by a read operation, there always exist two histories \( \mathcal{H}^* \) and \( \mathcal{H} \), and a
transaction $T_h$ such that $\mathcal{H}^*$ and $\bar{\mathcal{H}}$ are indistinguishable for $T_h$ and $T_h$ violates WRTO in $\mathcal{H}$. The two histories are defined as $\mathcal{H}^* = b_h, b_q, W_q(x_q), c_q, R_h(x_0), c_h$ and $\mathcal{H} = b_q, W_q(x_q), c_q, b_h, R_h(x_0), c_h$ (where we assume that $x_0$ is the initial value of $x$), and we say that they are indistinguishable for $T_h$ because the operations of $T_h$ perform the same steps (i.e., returns the same values) in both histories.

Note that $T_h$ must commit in both histories because it is wait-free (as it is a read-only transaction). In addition, $T_q$ must commit because it is obstruction-free and it has the opportunity to run solo in both histories.

Now we show that always reading the last available version of an object causes the violation of RTO, thus contradicting the hypothesis. In fact, a TM adopting that policy can accept history $\mathcal{H}_{WRTO}$ depicted in Figure 1, where $T_4$ is a read-only transaction and $y_0$ is the initial version of $y$. History $\mathcal{H}_{WRTO}$ does not preserve RTO because i) $T_3 \sim_{RTO}^{H_{WRTO}} T_2$ and ii) there exists the oriented path $T_2 \xrightarrow{wr} T_4 \xrightarrow{rw} T_3$ from $T_2$ to $T_3$ in $DSG(\mathcal{H}_{WRTO})$.

Note that, in the execution that generates $\mathcal{H}_{WRTO}$, $T_3$ cannot abort even if the TM accepts visible read-only transactions, otherwise the TM would not guarantee obstruction-free update transactions. This follows by the fact that: i) $T_3$ is not able to distinguish between an execution that generates $\mathcal{H}_{WRTO}$ and an execution in which $T_3$ commits before $T_3$ begins; ii) $T_3$ cannot wait for the commit of $T_4$, otherwise the execution of $T_3$ is slowed down due to possible interruption (or crash) of the execution of the process running $T_4$.

Therefore we have showed that a WDAP, obstruction-free TM, that guarantees WFRO and at least WRTO, can always generate a history like $\mathcal{H}_{WRTO}$ that violates RTO. Hence a WDAP, obstruction-free TM, that guarantees WFRO, does not preserve RTO, namely $\exists \mathcal{H}$ accepted by the TM such that $\mathcal{H}$ does not preserve RTO.

In the next result we analyze the possibility to have real-time order when considering weak progressiveness as the progress guarantee for write transactions. The answer is still negative (Theorem 2) if we require WFIRO, namely wait-free and invisible read-only transactions. The idea behind the proof follows the one of Theorem 1 and considers also that write transactions cannot detect a conflict with read-only transactions due to the invisibility of the latter. For space constraints we leave the proof of Theorem 2 in the Appendix.

**Theorem 2** Given a WDAP, weakly-progressive TM, that guarantees WFIRO, $\exists \mathcal{H}$ accepted by the TM such that $\mathcal{H}$ does not preserve RTO.

Interestingly there exists a SDAP TM implementation proposed in [3] that guarantees Opacity (and hence RTO), and which can be easily shown to ensure WFRO. However, this TM adopts visible read-only transactions (hence not contradicting Theorem 2), because their execution needs to block the commit of concurrent and conflicting write transactions.

Another SDAP TM implementation that also guarantees invisible read-only and strongly progressive transactions while preserving Opacity is TLC [5]. However TLC is not able to guarantee wait-free read-only transactions, thus again one of the hypothesis of Theorem 2 is not met by that algorithm.

## 4 A SDAP TM with Real-Time Order of Conflicting Transactions

In [4], authors prove that it is impossible to combine WDAP and WFIRO in a TM implementation that guarantees (Strict) Serializability [23] or Snapshot Isolation [6]. Since these properties are still highly desirable, in this section we look for the strongest consistency criterion among those included in the Adya’s hierarchy that a TM can ensure while preserving meaningful progress guarantee for update transactions.

As for what concerns RTO, our result in Theorem 2 assesses the impossibility of implementing a WDAP TM that guarantees WFIRO, RTO, even assuming a very weak progress criterion such as weakly progressive write transactions.

In the light of this set of impossibility results we target as consistency criterion EUS combined with WRTO. The choice of these consistency levels allows us to design a SDAP TM algorithm, which enforces WFIRO and guarantees strong progressiveness for update transactions. We note that the impossibility result in [8] prevents
our algorithm from being able to achieve obstruction freedom, as it guarantees EUS (which is stronger than Weak Adaptive Consistency) and SDAP.

In the following algorithm we rely on vector clocks as identifiers of the snapshots committed and as references to select the right versions during read operations. Specifically, each process \( p_i \) maintains a vector clock, \( \text{maxS} \), where \( \text{maxS}[k] \) records the maximum timestamp of process \( p_k \) as seen by \( p_i \); and a scalar, \( \text{tc} \), that stores the timestamp associated to the last commit of process \( p_i \). In addition, each transaction \( T_i \) has also a vector clock, \( \text{upperS} \), where \( \text{upperS}[k] \) represents the bound that \( T_i \) cannot exceed when reading a version written by process \( p_k \).

To univocally identify the commits in a totally decentralized way, each version is associated with two identifiers, i.e., \( \text{cid} \) and \( S \). The former is the identifier of the process having committed that version, while the latter is the vector clock the identifies the committed snapshot containing the version.

The central idea behind the proposed algorithm is similar to the one of the SDAP extension of TL2 presented in [5], i.e., TLC. Both protocols, in fact, ensure SDAP since transactions can only synchronize on public data structures, e.g., \( \text{cid} \) and \( S \), associated with transactional objects and only if they execute read/write operations on those objects. Further, unlike TLC, our proposal is able to guarantee that read-only transactions always commit because their read operations always return the right version belonging to the last committed consistent snapshot that they can observe without violating EUS or WRTO.

Throughout the description of the algorithm the binary relation \( \leq \) is used to define an order for both scalar values and vector clock values. In case of scalar values the relation is the standard less-than-or-equal relation defined for natural numbers. On the contrary, in case of vector clock values the relation has the meaning defined as follows. For each pair of vector clock values \( v_1, v_2 \), the pair \( \langle v_1, v_2 \rangle \) is in \( \leq \), by also writing \( v_1 \leq v_2 \), if \( \forall i, v_1[i] \leq v_2[i] \). If there exists also an index \( j \) such that \( v_1[j] < v_2[j] \), where \( < \) is the standard less relation defined for natural numbers, then \( v_1 \) \( < \) \( v_2 \) holds.

Handling read and write operations. Now we focus on the key aspects of the protocol. The read operation (see Algorithm 1) on \( x \) of transaction \( T_i \) is responsible for seeking the appropriate object version to read, according to the transaction’s history. Clearly, if \( x \) has been previously written by \( T_i \), the read operation returns the written value. Otherwise, the versions chain associated with \( x \) is traversed from the newest committed version to the oldest one. Specifically for each version \( \text{ver} \), the vector clocks \( \text{upperS} \) and \( \text{maxS} \) are compared to \( \text{ver} \)'s snapshot \( S \). If \( \text{maxS} \leq S \), which means that the process that is executing \( T_i \) has already observed a snapshot at least as recent as \( S \), then \( \text{ver} \) can be observed by the read of \( T_i \). There are two scenarios in

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**Algorithm 1** Read operation of transaction \( T_x \) on process \( p_i \)

1:  Val read(T tx, Var v)
2:  if \( \exists \text{val}' \) : \( v \ll \text{val}' \) \( \in \) tx.writeSet then
3:    return \( \text{val}' \)
4:  [Val result, bool mostRecent] \( \leftarrow \) doRead(tx, v)
5:  if tx.writeSet \( \neq \phi \) \&\& mostRecent = \( \perp \) then
6:    abort(tx)
7:  else
8:    return result
9:  end if
10: [Val bool] doRead(T tx, Var v)
11:  Version ver \( \leftarrow v\text{.mostRecentVers} \)
12:  while nonVisible(tx, ver) \cup unsafe(tx, ver, v) do
13:    if tx.upperS[ver.cid] \geq ver.S[ver.cid] then
14:      tx.upperS[ver.cid] \leftarrow ver.S[ver.cid] \( - \) 1
15:      ver \( \leftarrow \) ver.prev
16:    end while
17:  p_i.maxS[ver.cid] \leftarrow max(p_i.maxS[ver.cid], ver.S[ver.cid])
18:  tx.readSet \leftarrow tx.readSet \cup \langle v, ver \rangle
19:  return \[ ver.value, ver = v\text{.mostRecentVers} \]
20: end while
21:
22:  bool nonVisible(T tx, Version ver)
23:  if \( \exists k: \) tx.upperS[k] \( \neq \) 1 \&\& tx.upperS[k] \( < \) ver.S[k] then
24:    return \( \top \)
25:  return \( \perp \)
26:
27:  bool unsafe(T tx, Ver vers, Var v)
28:  if \( \exists k: p_i\text{.maxS}[k] \) \( < \) ver.S[k] then
29:    if locked(v) then
30:      return \( \top \)
31:    for all \( v, \) version \( \geq \) tx.readSet do
32:      if overwritten(tx, v, version, ver) then
33:        return \( \top \)
34:    return \( \perp \)
35:
36:  bool overwritten(T tx, Var vRead, Version verRead, Version target)
37:  Version curr \( \leftarrow v\text{Read.mostRecentVers} \)
38:  while curr \( \neq ver\text{Read} \) do
39:    if curr.S \( \leq \) target.S then
40:      return \( \top \)
41:    end while
42:  return \( \perp \)
which the current version could not be readable by $T_i$: when $upperS < S$ on the significant entries (i.e., those different from -1), or when $maxS$ is less than or not comparable with $S$. In these scenarios, in fact, reading the version could lead to a history that violates EUS. In the former scenario, $T_i$ cannot read $ver$ because it belongs to a snapshot already skipped by $T_i$ in a previous read, which has serialized $T_i$ before the transaction that committed the snapshot $S$ (that includes version $ver$). In the latter scenario, $T_i$ has to check if by reading version $ver$, which implies serializing $T_i$ after the transaction $T'$ that committed $ver$, it is still possible to serialize all the reads already performed by the transaction after $T'$ (which is tracked by advancing $maxS$ to $S$). For this reason, a re-validation of the read-set of $T_i$ is needed to check if there exists a version $ver^*$ that has been committed after any version in $T_i$’s read-set, and the snapshot that contains $ver^*$ is serialized before the snapshot that contains $ver$ (which can be determined by comparing the vector clocks of their snapshots $S$). In this aspect, the proposed algorithm shares similarities with LSA [26], which also forces a re-validation of the read-set in analogous circumstances, but which relies on a shared global clock and is therefore non-DAP.

After each read operation, $maxS$ is updated by computing the maximum between the snapshot $S$ of the returned version and the current transaction’s $maxS$. Finally the transaction keeps track of the read version through the read-set. During a read operation only write transactions can be aborted if they cannot access the newest version of read object.

The write operation is straightforward. It logs only the written object in the transaction’s write-set and, in case a write is executed multiple times on the same object, only the last value is maintained in the write-set.

**Handling commit operation.** When a transaction tries to commit (see Algorithm 2), it tries to acquire an exclusive lock on each object stored in its write-set, thus it can safely add a new version to the chain. If at least one of the lock acquisitions fails the transaction immediately aborts. After that, transaction tries to acquire shared locks on the objects listed in its read-set. As before, a failed lock acquisition triggers the abort of the transaction. Only after a successful acquisition of all the requested locks, the transaction validates its read-set (by checking that the read versions are the last committed ones) and flushes the write-set into shared memory, as in classical multi-version TM implementations [26, 10].

Finally the snapshot $S$ of each newly committed version (i.e., $newS$ in the pseudocode) results in a vector clock greater than all the most recent committed snapshots associated with the objects in the read-set and write-set. Further, the $cid$ of those versions is equal to the identifier of the process executing the committing transaction.

For space constraint we have to insert the correctness proof of the algorithm in the Appendix. Concerning liveness guarantees, the presented algorithm ensures wait-free read-only transactions (recall that we are assuming parasitic-free histories, see Section 2) and strong progressive update transactions. The former follows trivially from that we never block or abort a read-only transaction. As for update transactions, they achieve strong progressiveness as the commit scheme that they adopt follows the lock-based scheme implemented in TL2 [12], which has been already proved to guarantee strong progressiveness in [17].
To guarantee Consistent View, the TM has to ensure that every accepted history is dom or weak-progressiveness for the update transactions, then the space complexity for each version of a datum is \( \Omega(\text{m}) \), where \( \text{m} = \min(N_o, N_p) \).

**Theorem 3** Given a SDAP TM that guarantees WFIRO, Consistent View, WRTO and either obstruction freedom or weak-progressiveness for the update transactions, then the space complexity for each version of a datum is \( \Omega(\text{m}) \), where \( \text{m} = \min(N_o, N_p) \).

**Proof.** To guarantee Consistent View, the TM has to ensure that every accepted history \( \mathcal{H} \) does not contain a cycle \( C \) with exactly one anti-dependence edge in the \( DSG(\mathcal{H}) \). We assume that an initial version of each data item \( d \) exists in the TM, which we denote with \( d_0 \). Now consider the history \( \mathcal{H} \) whose \( DSG(\mathcal{H}) \) is shown in Figure 2, in which the first transaction to execute in absence of concurrency is \( T_q \), which commits version \( x_q \). As we are assuming obstruction-freedom or weak-progressiveness, the TM cannot refuse \( T_q \)’s commit.

Next in \( \mathcal{H} \) a read-only transaction \( T_{ro} \) issues a read on object \( x \). As we are assuming WFIRO, the read operation of \( T_{ro} \) must eventually return some value. Assume, with no loss of generality, that the value \( x_q \) is returned. Next, and before \( T_{ro} \) takes any other step (e.g., because it was descheduled), transaction \( T_j \) starts, writes \( x_j \) and \( d_1^j \) (where we assume object \( d^1 \neq x \)) and commits (we will shortly prove that this commit cannot be rejected by the TM). Following the commit of \( T_j \), the set of update transactions \( T = \{T_1, \ldots, T_i, \ldots, T_{s-1}, T_s\} \) is executed sequentially. Each transaction \( T_i \in T \) issues the following operations in \( \mathcal{H} \): \( T_i \) starts, reads a object \( d^i \), writes a different object \( d^{i+1} \), and requests to commit. We further assume that each transaction \( T_i \) runs solo, i.e. \( T_{i+1} \) starts only after \( T_i \) commits. As we are assuming that transaction \( T_1 \) and the transactions in \( T \) run solo, they must commit if we assume obstruction-freedom. If we assume weak-progressiveness, on the other hand, \( T_j \) may abort due to the presence of anti-dependence from \( T_{ro} \). However, since we are assuming invisible read-only transactions, \( T_j \) cannot detect the occurrence of this conflict, and, also in this case, it cannot abort.

Now assume that \( T_{ro} \) issues a read operation on object \( d^{s+1} \). At this point, as \( T_s \) committed version \( d^{s+1} \), \( T_{ro} \) needs to decide whether to observe this version. Note that since \( T_{ro} \) has already developed an anti-dependence towards \( T_1 \), if \( T_{ro} \) observed \( d^{s+1} \), Consistent View would be violated, as a cycle with exactly one anti-dependence would be created. Also, since we are assuming that the TM ensures WRTO, it cannot deterministically return the initial version \( d^{s+1}_0 \). In fact, using such a deterministic policy, it is straightforward to show that a read-only transaction \( T' \) may trivially miss the version committed by an update transaction that commits before \( T' \) starts.

![Figure 2: Read-only transaction \( T_i \) creating a cycle \( C \) with exactly one anti-dependence edge in \( DSG(\mathcal{H}) \).](image-url)
Also, in the assumed history, $T_{ro}$ cannot be aware of having developed an anti-dependence towards $T_j$, as we are assuming IRO. Hence, by no means, $T_{ro}$ could have transmitted any information to $T_j$ on the execution of its read on $x_q$. Further, no other transaction could have notified $T_{ro}$ of the existence of such anti-dependence.

Note that if $T_{ro}$ ignored the possibility of having developed new anti-dependences when determining the visibility of $d^\omega_{s+1}$, it could miss cycle $C$, and violate Consistent View. It follows that $T_{ro}$ has to first validate its current read-set, which comprises only $x_q$. This allows $T_{ro}$ to detect the anti-dependence with $T_j$, and poses $T_{ro}$ with the problem to determine whether there exists an oriented path from $T_j$ to $T_s$ (in which case $d^\omega_{s+1}$ should not be observed). Note that since we are assuming a SDAP TM, $T_{ro}$ needs to detect the existence of a path of direct dependencies from $T_j$ to $T_s$, without however being able to query any of the base objects that the transactions $T_1, \ldots, T_{s-1}$ accessed (as $T_{ro}$ accesses a disjoint data set with respect to these transactions).

In a SDAP TM in fact the only way for transactions to transmit information concerning the conflicts that they develop is via the base objects associated with the transactional objects that they access. The transmission of this information can be emulated considering a distributed message passing system (DS) comprising the same number of processes considered in the TM, namely $N_p$. Consider, in particular, the following simulation: for each direct read-dependence edge $T_i \xrightarrow{w} T_{i+1} \in \text{DSG}(H)$, developed by a pair of write/read operations on version $d^i_{i+1}$ of transactional object $d^i_{i+1}$, we can associate the events of send, resp. receive, of a message $m_{i,i+1}$ in DS from $p_i$, resp. to $p_{i+1}$. Since the communication of any type of information on the ordering of events in a SDAP TM can only take place via base objects, this can be simulated in the DS by assuming that $m_{i,i+1}$ can only be tagged with the information that $T_i$ had stored in the base object associated with version $d^i_{i+1}$, at the time in which $T_i$ created it. Analogously for the direct anti-dependence edge $T_i \xrightarrow{rw} T_j \in \text{DSG}(H)$, developed by the operations $R(x_q)$ and $W(x_j)$, we can associate the events of send, resp. receive, of a message $m_{j,i}$ in DS from $p_j$, resp. to $p_{ro}$. What triggers the sending of this message in this history is the fact that $T_{ro}$ has to access the base object of $x_j$ (and of all existing versions of $x$) in order to validate its read-set.

With this simulation we have transformed the problem of determining whether there exists a path from $T_j$ to $T_s$ in $\text{DSG}(H)$ based on the information available to $T_{ro}$, to the problem of having the process $p_{ro}$ (that executes transaction $T_{ro}$) in DS to determine whether the two messages $m_{j,i}$ and $m_{s,i}$ are causally ordered [21], namely $m_{j,i} \prec_{DS} m_{s,i}$. Thanks to the result in [14, 22], in a distributed system of $N_p$ processes such as $\text{DS}_{TM}$, given two events $e$ and $e'$, $e \prec_{DS} e'$ iff $\Theta(e) < \Theta(e')$, where $\Theta(e)$ (respectively $\Theta(e')$) is the vector clock of size $N_p$ associated to event $e$ (respectively $e'$). Hence, the base objects, which represent the only way to exchange information on the relative ordering of operations in a SDAP TM, need to have a space capacity equals [11] to $\Omega(N_p)$.

An alternative approach to encode the entire set of dependencies developed by a transaction $T$ during its execution is to store in the base objects associated to the versions created by $T$ a vector containing a scalar for each transactional object in the TM (hence vector clocks have size equal to $N_o$). A TM implementing such a technique is for instance shown in Ardekani et al. [2], and is based on the idea of tracking in the $d$-th entry of a base object associated with an object version created by transaction $T$, a scalar that identifies the version of $d$ that is visible to $T$.

To summarize, we have shown that a lower bound on the spatial cost for the base objects of a SDAP TM that guarantees Consistent View, WFIRO, WRTO and obstruction-freedom (or weak-progressiveness), is $\Omega(m)$, where $m = \min(N_o, N_p)$.

It should be noted that, whenever the number of processes is less than the number of shared objects (which is normally the case), the algorithm presented in Section 4 meets this lower bound and is therefore optimal.

### 6 Relations with Existing Impossibility Results

The result of Theorem 1 enriches the result showed in [4] because the lower bound defined on the number of write operations that have to be executed by read-only transactions in a Strict Serializable and WDAP TM with
obstruction-free write transactions, is only a necessary condition to ensure wait-free read-only transactions. In fact, our result is independent of the visibility of read-only transactions and states that such a TM does not preserve the real-time order. Since Strict Serializability demands that the equivalent serialization order of committed transactions also preserves real-time order among them [23, 16], by Theorem 1 no WDAP TM with obstruction-free write transactions and wait-free read-only transactions can ever guarantee Strict Serializability even by applying the number of non-trivial, i.e., write, operations in the read-only transactions according to the lower bound in Attiya et al. [4].

In Perelman et al. [25], the authors prove that a WDAP TM cannot guarantee MV-permissiveness and Strict Serializability. MV-permissiveness allows only write transactions to abort due to conflicts with other write transactions, and therefore it guarantees that read-only transactions are not forcefully aborted. If we suppose a parasitic-free system, this property defines liveness guarantees for both read-only and write transactions. In particular, on one side by ensuring that a transaction eventually requests to commit, MV-permissiveness implies wait-free read-only transactions; on the other side, since write transactions may be forcefully aborted due to a conflict with other write transactions, the property entails weakly progressive write transactions. Furthermore the authors propose the invisibility of read-only transactions since they cannot either abort or block the execution of concurrent write transactions. Therefore the impossibility presented in Perelman et al. [25] use the same assumptions of Theorem 2 and proves that such a TM cannot guarantee Strict Serializability. However the result is weaker than the one of Theorem 2, because the latter states that the impossibility to combine WDAP, wait-free invisible read-only transactions and weakly progressive write transactions is due to the real-time order, and it is independent of the isolation level required, e.g. Serializability.

The impossibility result by Guerraoui and Kapalka [15] rules out any possibility to combine a SDAP TM and obstruction-free transactions if the target isolation level is Serializability. This is because, besides the formal proof, the paper shows an execution as a counterexample to support the proof that we can use as is to extend the result to EUS as well. The authors consider an execution admitted by obstruction-free TM implementations with 3 write transactions $T_1$, $T_2$, $T_3$ such that: (i) $T_2$ and $T_3$ must commit because of the obstruction-freedom condition, (ii) the commit of $T_1$ would violate Serializability of the resulting history and (iii) the abort of $T_1$ would violate the SDAP condition. Since the example only considers write transactions and proves that is impossible to combine Serializability of write transactions with obstruction-freedom in a SDAP TM, we could not consider obstruction-free as target liveness property for write transactions in the TM presented in Section 4, because EUS demands committed write transactions to be Serializable.

This same impossibility result [15] has been recently superseded by the results of the PCL theorem [8]. The theorem proves that transactions cannot be parallel, consistent and live even by assuming obstruction-freedom and Weak Adaptive Consistency — a consistency criterion even weaker than Processor Consistency and Snapshot Isolation. The proposed SDAP implementation of TM overcomes this impossibility result by assuming a different liveness property. In particular, by changing the liveness from obstruction-freedom to strong progressiveness of only write transactions we are able to ensure: (i) the maximum level of liveness for read-only transactions without enforcing their visibility; (ii) a consistency criterion that is close to Opacity and combines EUS and WRTO.

7 Conclusion

We presented a possibility, as well as two impossibility results about implementing DAP TMs that ensure efficient (i.e., wait-free and invisible) read-only transactions. On one side, we presented a protocol proving the feasibility of building a SDAP TM, combined with invisible and wait-free read-only transactions, and preserving EUS (a consistency criterion that provides guarantees very close to Opacity and Virtual World Consistency) and WRTO (a variant of classic real-time order restricted to conflicting transactions). In addition, we derived a lower bound on the space complexity of implementing a SDAP TM that guarantees EUS, WRTO, WFIRO and obstruction freedom (or weak progressiveness). We also proved that ensuring real-time order and DAP is impossible independently of the assumed isolation criterion and considering different liveness criteria.
References


Appendix

**Theorem 2** Given a WDAP, weakly-progressive TM, that guarantees WFIRO, ∃H accepted by the TM such that H does not preserve RTO.

**Proof.** The proof follows by contradiction and throughout the proof we assume that two different transactions are executed by two distinct processes. We assume by contradiction that ∀H accepted by the TM H preserves RTO. Hence, the TM must at least preserve WRTO. As showed in the proof of Theorem 1, this is possible only if the read policy implemented in the WDAP TM ensures that transactions always read the last available version of an object. But if this is the case, the TM can accept history HWRTO depicted in Figure 1, where T4 is a read-only transaction and y0 is the initial version of y. History HWRTO does not preserve RTO because i) T3 RTO T2 and ii) there exists the oriented path T2 WRTO T1 WRTO T3 from T2 to T3 in DSG(HWRTO).

Note that, even if the TM guarantees weakly progressive write transactions, Tq and Tk cannot abort in HWRTO because they cannot detect their conflict with Th, as read-only transaction Th is invisible according to the hypothesis.

Therefore we have showed that a WDAP, weakly progressive TM, that guarantees WFIRO and at least WRTO, can always generate a history like HWRTO that violates RTO. As a consequence a WDAP, weakly progressive TM, that guarantees WFIRO, does not preserve RTO, namely ∃H accepted by the TM such that H does not preserve RTO. □

![Figure 3: Write and read operations a transaction on process pi simulated by DS_{TM}.](image)

**Lemma 1** Given a SDAP, multi-version TM that guarantees PL-2 isolation level, wait-free and invisible read-only transactions and has Np processes that execute transactions, we can build a message-passing distributed system DS_{TM} with Np processes, such that:

1. ∀i, q and object x, the DS_{TM} has a sequence of events that simulate the operations R_i(x_q) and W_i(x_i).
2. Given p_i and p_j, two processes executing respectively transactions T_q and T_h and history H executed by TM such that T_h ∈ H and T_h ∈ H, if T_q WRTO T_h ∈ DSG(H) or T_q WRTO T_h ∈ DSG(H) then for each pair of objects x, y (with possibly x equals to y),
   - if W_q(x_q) ∈ H and W_h(y_h) ∈ H ⇒ e_i^{W_q(x_q)} <_{DS} e_j^{W_h(y_h)}.

The events e_i^{W_q(x_q)}, e_j^{W_h(y_h)} are the events that simulate the finalization respectively of the write operation W_q(x_q) of T_q on the process p_i in DS_{TM} and of the write operation W_h(y_h) of T_h on the process p_j in DS_{TM}. The <_{DS} is the happened-before relation in DS_{TM} as defined in [21].

**Proof.** We can build the distributed system DS_{TM} as follows: for each process p_i running transactions, we have a process p_i in DS_{TM}. Processes in DS_{TM} can communicate only by exchanging messages. Since the TM is SDAP we allow two processes in DS_{TM} to exchange messages only if the associated processes in the TM execute conflicting transactions. To do so, we associate with process p_i, a version x_k of object x if the corresponding process in TM runs a transaction T_k that executes a write operation W_k(x_k). Note that the DS_{TM} does not simulate read operations of read-only transactions since those are invisible. Operations executed by write transactions in TM are simulated in DS_{TM} as listed below.

![Figure 3: Write and read operations a transaction on process pi simulated by DS_{TM}.](image)
Write operation \(W_i(x_i)\). Process \(p_i\) in TM runs transaction \(T_i\) that writes version \(x_i\) of object \(x\). We suppose that the last version of \(x\) before this write operation is \(x_q\). In addition \(x_q\) has been previously written by transaction \(T_q\) in execution on process \(p_q\). Then \(DS_{TM}\) executes the following steps as in Figure 3(a): i) \(p_i\) sends a message \(m\) to \(p_j\) by means of the event \(e^i_{send(W,x)}\) in order to simulate that \(T_i\) writes after \(T_q\) on \(x\); ii) \(p_j\) sends a message \(m'\) to \(p_i\) by means of the event \(e^j_{send(W,x)}\) after the event \(e^j_{receive(W,x)}\) on the reception of message \(m\); iii) \(p_i\) generates the event \(e^i_{W_i(x_i)}\) after the event \(e^j_{receive(W,x)}\) on the reception of message \(m'\).

Since the previous write operation \(W_q(x_q)\) is completed in \(DS_{TM}\) by means of the event \(e^j_{W_q(x_q)}\) and before the event \(e^j_{receive(W,x)}\), it follows that \(e^j_{W_q(x_q)} \prec DS e^j_{W_i(x_i)}\).

Read operation \(R_i(x_i)\). Process \(p_i\) in TM runs transaction \(T_i\) that reads version \(x_i\) of object \(x\). We suppose that transaction \(T_q\) writes \(x_q\) and process \(p_j\) runs \(T_q\). Then \(DS_{TM}\) executes the following steps as in Figure 3(b): i) \(p_i\) sends a message \(m\) to \(p_j\) by means of the event \(e^i_{send(R,x)}\); ii) \(p_j\) sends a message \(m'\) to \(p_i\) by means of the event \(e^j_{send(R,x)}\) after the event \(e^j_{receive(R,x)}\) on the reception of message \(m\); iii) \(p_i\) generates the event \(e^i_{R_i(x_i)}\) after the event \(e^j_{receive(R,x)}\) on the reception of message \(m'\). Since the write operation \(W_q(x_q)\) is completed in \(DS_{TM}\) by means of the event \(e^j_{W_q(x_q)}\) and before the event \(e^j_{receive(R,x)}\), it follows that \(e^j_{W_q(x_q)} \prec DS e^i_{R_i(x_i)}\).

Following the above rules, we have showed (th1) how to build \(DS_{TM}\) on a SDAP TM with invisible read-only transactions.

Now we prove th2 by contradiction. We assume by a way of contradiction that, given a SDAP, multi-version TM that guarantees wait-free and invisible read-only transactions, for each history \(H\) if \(T_q \xrightarrow{wir} T_h \in DSG(H) \lor T_q \xrightarrow{wir} T_h \in DSG(H)\) and there exist two write operations \(W_q(x_q) \in H\) and \(W_h(y_h) \in H\) such that \(e^j_{W_q(x_q)} \prec DS e^i_{W_q(x_q)} \land e^i_{W_q(x_q)} \parallel e^j_{W_h(y_h)}\), then \(H\) may violate the PL-2 isolation level. We use \(e^i_{W_q(x_q)} \parallel e^j_{W_h(y_h)}\) to state that neither \(e^j_{W_q(x_q)} \prec DS e^i_{W_q(x_q)}\) nor \(e^j_{W_q(x_q)} \prec DS e^j_{W_h(y_h)}\) hold.

In particular we distinguish two cases:

- \(e^j_{W_q(x_q)} \prec DS e^i_{W_q(x_q)}\). Then there may exist a transaction \(T_k\) such that \(W_k(y_k) \in H\), where \(y_h \ll y_k\), and \(W_k(x_k) \in H\), where \(x_k \ll x_q\). We suppose that \(T_k\) executes after \(T_q\) on \(x_k\). This is admissible because there exists a process \(p_l\) in \(DS_{TM}\) that generates two events \(e^i_{W_k(y_k)}\) and \(e^i_{W_k(x_k)}\) such that \(e^i_{W_k(y_k)} \prec DS e^j_{W_k(y_k)}\), \(e^i_{W_k(x_k)} \prec DS e^i_{W_k(x_k)}\).

- \(e^i_{W_q(x_q)} \parallel e^j_{W_h(y_h)}\). Then there may exist a transaction \(T_k\) such that \(W_k(y_k) \in H\), where \(y_h \ll y_k\), and \(W_k(x_k) \in H\), where \(x_k \ll x_q\). We suppose that \(T_k\) executes before \(T_q\) on \(x_k\). This is admissible because \(e^i_{W_q(x_q)} \parallel e^i_{W_h(y_h)}\), and therefore there exists a process \(p_l\) in \(DS_{TM}\) that generates two events \(e^i_{W_k(y_k)}\) and \(e^i_{W_k(x_k)}\) such that \(e^i_{W_k(y_k)} \prec DS e^i_{W_k(y_k)}\), \(e^j_{W_h(y_h)} \prec DS e^j_{W_h(y_h)}\), \(e^j_{W_k(x_k)} \prec DS e^i_{W_k(x_k)}\).

However in both cases transactions \(T_h\), \(T_q\) and \(T_k\) generate a cycle of dependencies in \(DSG(H)\), i.e. \(T_q \xrightarrow{wir/wr} T_h \xrightarrow{wir} T_k \xrightarrow{wir} T_q\), and this contradicts the hypothesis of an TM that guarantees PL-2 isolation level [1].

**Algorithm Correctness proof**

In this Section we prove the correctness of the algorithm presented in Section 4 and therefore we prove that every history \(H\) accepted by the algorithm does not violate EUS. For the sake of clarity, throughout the proof we refer to the algorithm as \(A\). In addition we prove that every history \(H\) accepted by the algorithm does not violate WRTQ.

We recall that a history \(H\) does not violate EUS if the following anomalies are prevented (as defined in [1]):
- G1a. \(H\) contains the operations \(W_q(x_q)\), \(R_k(x_q)\) and \(a_q\). This means that transactions \(T_k\) has read a version written by an aborted transaction \(T_q\).
- G1b. \(H\) contains the operations \(W_q(x_q)\), \(R_k(x_q)\) and \(W_q(x_q)\) is not the last write of \(T_q\) on \(x\). This means that transaction \(T_k\) has read an intermediate non-committed value of \(x\).
- G1c. The $DSG(H^c)$ graph built on the history $H^c$ derived from $H$ by removing aborted and executing (i.e. ongoing) transactions contains an oriented cycle of all dependence edges.

- Extended G-update. The $DSG(H^upc_{T_k})$ graph built on the committed write transactions in $H$ plus transaction $T_k$ in $H$ contains an oriented cycle with one or more anti-dependence edges.

We use the prefix Extended for the G-update anomaly because $T_k$ is allowed to be either completed, thus aborted or committed, or ongoing. Note that EUS includes PL-2 isolation level, which prevents anomalies G1a, G1b and G1c, and Consistent View (PL-2+) isolation level because the G-update anomaly is more restrictive than the one characterizing Consistent View, i.e. the $DSG(H^c)$ graph contains an oriented cycle with exactly one anti-dependence edge.

We do not formally prove that $A$ avoids anomalies G1a and G1b because this is trivially guaranteed since i) for each object $x$ and transaction $T_k$, $T_k$’s write-set always contains only the outcome of the last write operation executed on $x$ by $T_k$ and ii) the $T_k$’s write-set is made available to read operations at commit time and only if $T_k$ commits.

The formal prove is organized as follows: we first prove that the history $H^{upc}$ derived from $H$ by removing aborted, executing (i.e. ongoing) and read-only transactions does not contain any oriented cycle, thus showing that $A$ prevents anomaly G1c and the anomaly Extended G-update where $T_k$ is a committed write transaction (Lemma 2); then we prove that the $DSG(H^upc_{T_k})$ graph does not contain any oriented cycle, where $T_k$ is a committed read-only transaction in $H$, thus showing that $A$ prevents anomaly Extended G-update where $T_k$ is a committed read-only transaction (Lemma 3). Finally the Theorem 4 concludes the formal proof by taking into account that an aborted or ongoing transaction at time $t$ can be considered as a committed read-only transaction constituted by its prefix at time $t$ that contains all its read operations performed until time $t$, except the read operation which has triggered an abort (if any).

**Lemma 2** For each history $H$ accepted by $A$, the $DSG(H^{upc})$ graph built on the history $H^{upc}$ derived from $H$ by removing aborted, executing (i.e. ongoing) and read-only transactions does not contain any oriented cycle.

**Proof.** The proof follows by contradiction. In particular we prove that if such a cycle exists, this violates the total order property on natural numbers. Therefore we suppose that the $DSG(H^{upc})$ contains an oriented cycle $C$. In addition, for each vertex $T_q$ in $C$, we associate: i) the vector clock $T_q.commitVC$ that is the $newS$ vector clock used by $T_q$ to commit new versions; ii) the vector clock $T_q.readVC$ that is the $T_q$’s $maxS$ vector clock at the time $T_q$ starts the commit phase.

Now we show that for each edge $T_q \rightarrow T_k \in C$, where $T_q$ and $T_k$ are committed update transactions in $H^{upc}$, $T_q.commitVC < T_k.commitVC$. Therefore we distinguish three cases depending on the type of dependence between $T_q$ and $T_k$:

- $T_q \xrightarrow{upc} T_k$. In this case there exists an object $x$ such that $W_q(x_q) \in H^{upc}$, $W_k(x_k) \in H^{upc}$ and $x_k < x_q$. Due to the lock acquisition on the objects in the write-sets, $T_q$ already committed when $T_k$ starts the commit. Therefore $T_q.commitVC < T_k.commitVC$ because: i) $T_k.commitVC \geq T_q.commitVC$ since $T_k$ builds $T_k.commitVC$ starting from $T_q.readVC$ and by means of a maximum operation among the vector clocks associated to the newest versions of the objects to be written; ii) there exists an index $j$ such that the $T_q.commitVC[j] > T_q.commitVC[j]$, where $p_j$ is the process executing $T_k$. The latter is true because $T_k$ increments by 1 the $j$-th entry of $T_k.commitVC$ before writing the new versions.

- $T_q \xrightarrow{wr} T_k$. In this case there exists an object $x$ such that $W_q(x_q) \in H^{upc}$, $R_k(x_q) \in H^{upc}$. Therefore the status of $T_k.readVC$ right after the execution of $R_k(x_q)$ is at least equals to $T_q.commitVC$ because $T_k.readVC$ is updated by means of $max(T_k.readVC, T_q.commitVC)$. In addition $T_k.commitVC > T_k.readVC$ because: i) $T_k$ builds $T_k.commitVC$ starting from $T_k.readVC$ and by means of a maximum operation among the vector clocks associated to the newest versions of the objects to be written; ii) there exists an index $j$ such that the $T_k.commitVC[j] > T_k.readVC[j]$, where $p_j$ is the process executing $T_k$, as proved for the previous case.

As a consequence $T_q.commitVC < T_k.commitVC$.

- $T_q \xrightarrow{rw} T_k$. In this case there exists an object $x$ such that $W_k(x_k) \in H^{upc}$, $R_q(x_q) \in H^{upc}$ and $x_k < x_q$. $T_q$ has completed its commit before the finalization of the commit of $T_k$ otherwise we would
have that: i) either \( T_q \) aborts due to a failed shared lock acquisition on \( x \) or validation of \( x \), or ii) \( T_k \) aborts due to a failed exclusive lock acquisition on \( x \). As in the first case, \( T_q \) and \( T_k \) are two conflicting update transactions where the commit of \( T_k \) follows the commit of \( T_q \). Therefore \( T_q-commitVC < T_k-commitVC \).

As a consequence if the cycle \( C \) exists we would have \( T_q-commitVC < T_q-commitVC \), where \( T_q \) is a vertex in \( C \), that is clearly impossible. Therefore the \( DSG(H^{sep}) \) graph does not contain any oriented cycle. \( \square \)

**Lemma 3** For each history \( H \) accepted by \( A \), the \( DSG(H^{sep}) \) graph built on the committed write transactions in \( H \) plus committed read-only transaction \( T_k \) in \( H \) does not contain any oriented cycle.

**Proof.** The proof follows by contradiction. In particular we prove that if such a cycle exists, this violates the total order property on natural numbers. Therefore we suppose that the \( DSG(H^{sep}) \) graph built on the committed transactions in \( H \) plus committed read-only transaction \( T_k \) in \( H \) contains an oriented cycle \( C \).

By the result of Lemma 2, \( C \) must involve the read-only transaction \( T_k \) because the \( DSG(H^{sep}) \) is acyclic. In addition, following the proof of Lemma 2, for each vertex \( T_q \) in \( C \), we associate: i) the vector clock \( T_q-commitVC \) that is the new vector clock used by \( T_q \) to commit new versions (if any); ii) the vector clock \( T_q-readVC \) that is the \( T_q \)'s max vector clock at the time \( T_q \) starts the commit phase.

As a consequence we prove that:
- for each committed update transaction \( T_q \) such that \( T_q \stackrel{wr}{\rightarrow} T_k \) is in \( C \), \( T_q-commitVC \leq T_k-readVC \);
- for each committed update transaction \( T_q \) such that \( T_k \stackrel{\cdots \cdots}{\rightarrow} T_q \) is in \( C \), there exists an index \( j \) such that \( T_k-readVC[j] < T_q-commitVC[j] \).

The former is verified because there exists an object \( x \) such that \( W_q(x_q) \in H^{sep} \), \( R_k(x_q) \in H^{sep} \) and the status of \( T_k-readVC \) right after the execution of \( R_k(x_q) \) is at least equals to \( T_q-commitVC \) since \( T_k-readVC \) is updated by means of \( \max(T_k-readVC, T_q-commitVC) \).

The latter is verified because there exists an object \( x \) such that \( W_q(x_q) \in H^{sep} \), and \( T_k \) skips version \( x_q \) when it executes \( R_k(x_h) \in H^{sep} \), where \( x_h \ll x_q \).

Afterwards by following the proof of Lemma 2, for each dependence or anti-dependence \( T_q \rightarrow T_h \), we have \( T_q-commitVC < T_h-commitVC \) if both \( T_q \) and \( T_h \) are committed write transactions.

As a consequence there exists an index \( j \) such that \( T_q-commitVC[j] < T_q-commitVC[j] \), for each committed write transaction in \( C \), and \( T_k-readVC[j] < T_k-readVC[j] \), which are both impossible.

Therefore we have proved that the \( DSG(H^{sep}) \) does not contain any oriented cycle. \( \square \)

**Theorem 4** For each history \( H \) accepted by \( A \), \( H \) does not violate EUS.

**Proof.** By Lemma 2 the history \( H^{sep} \) derived from \( H \) by removing aborted, executing and read-only transactions does not contain any oriented cycle. Since a cycle of all dependence edges cannot involve a read-only transaction, then the \( DSG(H^c) \) on \( H^c \) derived from \( H \) by removing aborted and executing transactions does not contain any oriented cycle of all dependence edges. In this way we have proved that \( H \) cannot generates anomaly G1c.

On the other side \( H \) cannot generates anomaly Extended G-update for the following reasons:
- The \( DSG(H^{sep}) \) graph built on the committed write transactions in \( H \) plus transaction \( T_k \) in \( H \) does not contain any oriented cycle with one or more anti-dependence edges if \( T_k \) is a committed write transaction. This follows by the Lemma 2, because in this case \( H^{sep} = H^{sep} \) and the \( DSG(H^{sep}) \) graph does not contain any oriented cycle.
- The \( DSG(H^{sep}) \) graph built on the committed transactions in \( H \) plus a committed read-only transaction \( T_k \) does not contain any oriented cycle by the result of Lemma 3 and therefore it does not contain any oriented cycle with one or more anti-dependence edges.
- The \( DSG(H^{sep}) \) graph built on the committed transactions in \( H \) plus an aborted or executing \( T_k \) does not contain any oriented cycle by the result of Lemma 3 and by considering that an executing or an aborted transaction at time \( t \) can be treated as a committed read-only transaction constituted by its prefix
at time $t$ that contains all its read operations performed until time $t$, except the read operation which has triggered an abort (if any). This is an admissible reduction since write operations are buffered during the execution of a transaction and they are externalized (i.e. the updates are applied) only upon a successfully completed commit phase.

Therefore the $DSG(H_{upc}^{T_k})$ graph does not contain any oriented cycle with one or more anti-dependence edges.

As a consequence we have proved that for each history $H$ accepted by $A$, $H$ does not violate EUS.  

\[ \square \]

**Theorem 5** $\forall H$ accepted by $A$, $H$ preserves WRTO.

**Proof.**

We suppose that $\exists H$ accepted by $A$ such that $H$ does not preserve the real-time order among conflicting transactions in $H$. Therefore there are two conflicting transactions $T_q$ and $T_k$ such that $T_q \prec_H T_k$ and at least one of the following condition is verified:

1. $\exists x$ such that both $W_q(x_q)$ and $W_k(x_k)$ are in $H$ and $x_k \ll x_q$.
2. $\exists x$ such that both $W_q(x_q)$ and $R_k(x_h)$ are in $H$ and $x_h \ll x_q$.

Condition 1. is impossible because:

- By nature of transactions if $T_q \prec_H T_k$ then $c_q \prec_H c_k$.
- $A$ applies write operations at commit time and only if a transaction successfully commits.
- In $A$ the total order on the versions of an object is defined by the total order of the commits on that object.

Therefore $x_q \ll x_k$ in $H$ that contradicts condition 1.

Condition 2. is impossible because:

- $A$ has forced the read of $x_h$ because $T_k$ could not read $x_q$ in $H$. This happens if there exists a version $y_r$ in $T_k$’s read-set and a version $y_t$, where $y_r \ll y_t$, such that the snapshot vector clock of $y_t$ is less than or equals to the snapshot vector clock of $x_q$, i.e. $y_t.snapshot \leq x_q.snapshot$. Without loss of generality we suppose that the read of $y_r$, i.e. $R_k(y_r)$, is the first read of $T_k$ and the read of $x_h$, i.e. $R_k(x_h)$ is the second one.

If that is the case the write operation on $y_t$ is executed after the write operation on $x_q$ because at the time $T_k$ executed its first read operation $R_k(y_r)$ it returned the most recent version of $y$ and it didn’t find version $y_t$. In addition at that time transaction $T_q$ had already committed since $T_q \prec_H T_k$. Therefore we have the contradiction such that the write on $y_t$ is executed after the write on $x_q$ and $y_t.snapshot \leq x_q.snapshot$. In fact, since $A$ can be simulated by the distributed system $DS_A$ (Lemma 1), we have that $e_W^q(x_q) \prec_{DS} e_W^q(y_t)$ and $y_t.snapshot > x_q.snapshot$.

Since we have proved that both conditions are impossible it must be that $\forall H$ accepted by $A$, $H$ preserves WRTO.  

\[ \square \]